

# Prim's Algorithm $(G, w, r)$

1.  $Q \leftarrow V$
2. for each  $u \in Q$
3.     do  $key[u] = \infty$
4.      $key[r] = 0$ .
5.      $\pi(r) = NIL$
6.     while  $Q \neq \emptyset$
7.         do  $u \leftarrow EXTRACT-MIN(Q)$
8.         for each  $v \in Adj[u]$
9.             do if  $v \in Q$  &  $w(u, v) < key[v]$
10.             then  $\pi(v) \leftarrow u$ .
11.              $key[v] \leftarrow w(u, v)$

$\log n$

|

1.  $X = \{ (v, \pi(v)) : v \in V - \{s\} - Q \}$

2.  $V - Q$  are the vertices of the tree

3. If  $v \in Q$  &  $\pi(v) \neq \text{NIL}$   
 $\text{Key}[v] < \infty$ .

$\text{Key}[v]$  gives the lightest cost  
connecting  $v$  to some vertex in  $X$ .

# Correctness & Complexity.

Correctness follows from the cut property.

Complexity of Prim's algorithm

depends on how you implement

the priority queue. If  $Q$  is

implemented as a binary heap

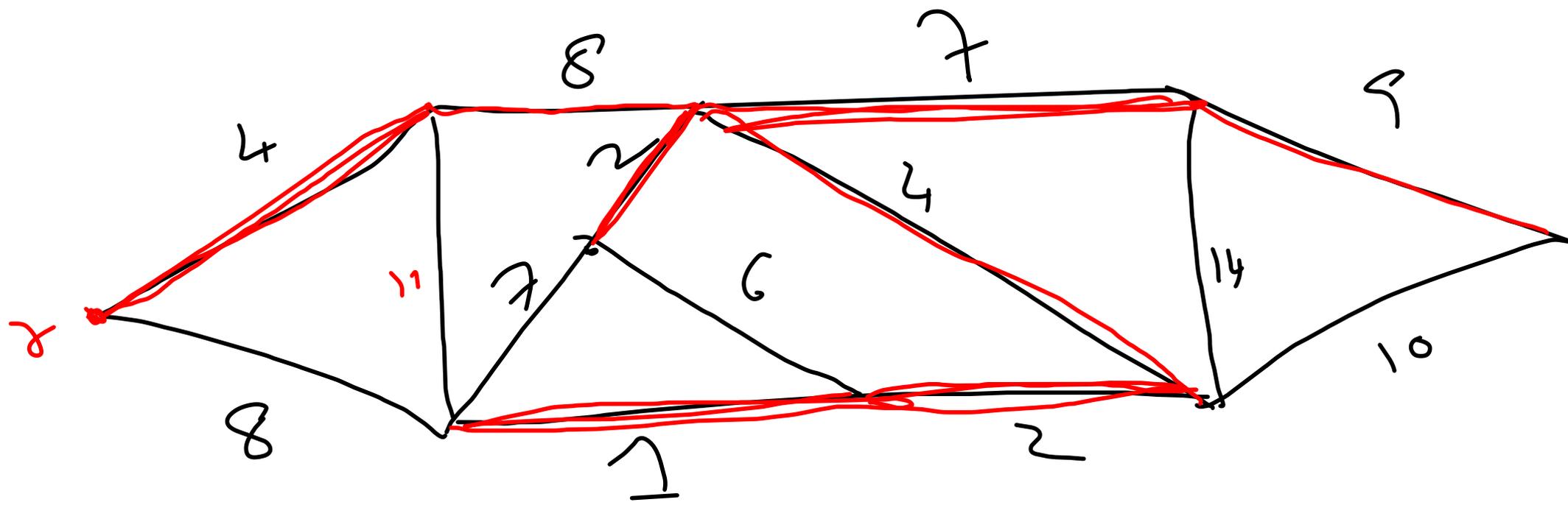
then line 7 takes  $O(\log n)$  time

Hence the while loop can be executed  
in  $O(n \log n)$  time.

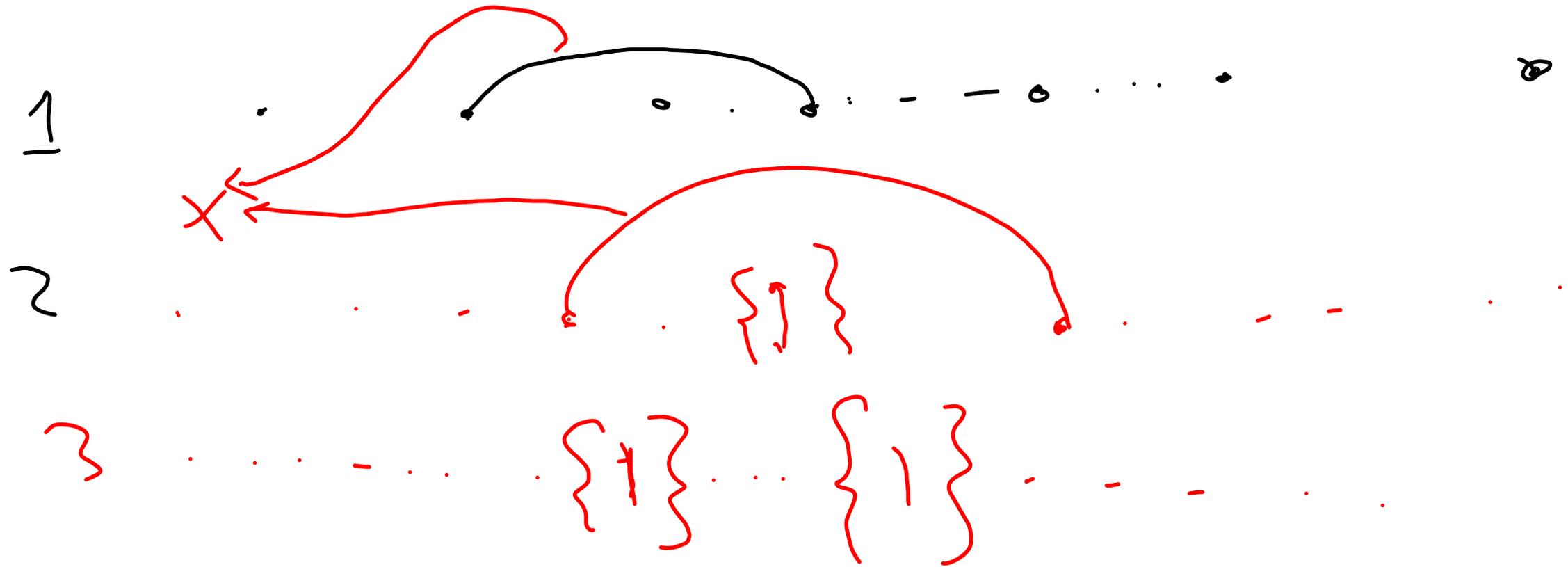
Updating the key can be  
implemented in  $O(\log n)$  time &

hence the for loop can be executed  
in  $O(e \log n)$  time.

Running time  $O(n \log n + e \log n) = O(e \log n)$



# Kruskal's Algorithm



Kruskal's alg. adopts a different strategy.

Instead of growing a single tree

Kruskal's alg. adds

a lightest possible edge to start

We sort the edges in order of

increasing wt. Initially  $x = \emptyset$

and each vertex in  $V$  is regarded

as a trivial tree. We ~~to~~ examine

Each edge in order & if end pts  
of this edge belong to the same  
tree we discard. Otherwise, this  
edge is added to  $X$ . This causes  
the two trees containing the end pts  
to merge into a single tree.

To implement, given a forest of trees,  
we need to decide given a pair  
of vertices if they belong to the same  
tree. For the purpose of implementation,  
each tree is regarded as a set of  
vertices of that tree. Our data structure  
should support merging of two trees.  
So the data structure should

maintain a collection of disjoint set  
A should support the following

1.  $\text{MAKESET}(x)$ : Create a set consisting of the single element  $x$ .
2.  $\text{FIND}(u)$ : Given  $u$ , it finds the set containing  $u$ .
3.  $\text{UNION}(u, v)$ : Replace the set containing  $u$  & the set containing  $v$  by their Union.

# Kruskal's Algorithm.

$X \leftarrow \emptyset$

Sort  $E$  by weight.

$\rightarrow O(|E| \log |E|)$  time.

for  $u, v$

MAKESET( $u$ )

end for

for  $(u, v) \in E$  in increasing order do

if FIND( $u$ )  $\neq$  FIND( $v$ )

$X \leftarrow X \cup \{(u, v)\}$ .

UNION( $u, v$ )

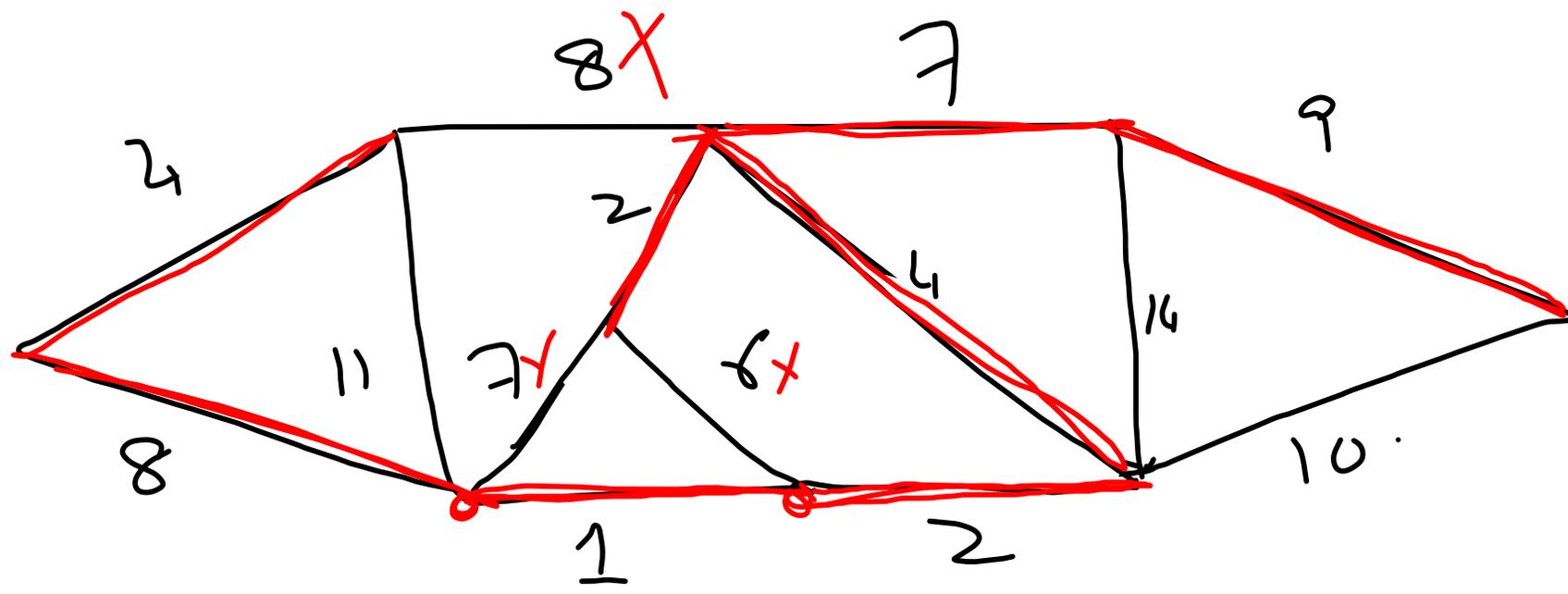
end for

return  $X$ .

# Complexity.

If we are given a sorted list of edges, then the running time is determined by  $n-1$  UNION of  $\alpha$   $\alpha$   $\alpha$  FIND operations. Using a fast UNION-FIND, this can be achieved in time  $O(e \log \alpha)$ .

If the edges are unsorted, the running time is  $O(e \log e)$ .

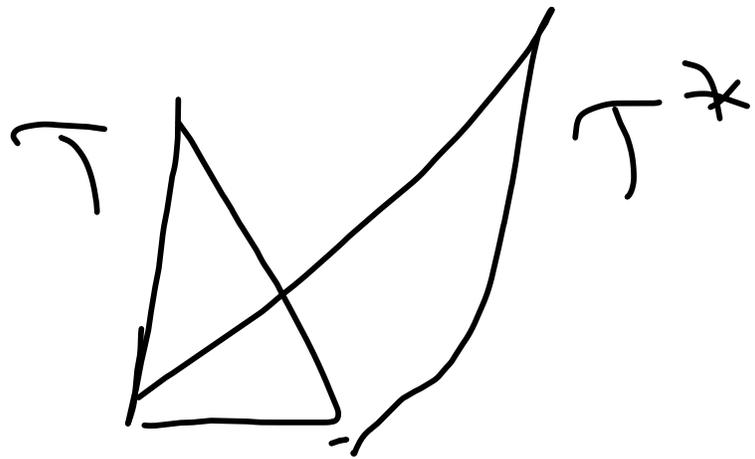


Ex 1 Show that if the wts. are distinct, then there is a unique MST

Ex 2 Prove the following exchange property for spanning trees.

- Let  $T$  &  $T'$  be spanning trees in  $G=(V, E)$   
Given an edge  $e' \in T' - T$ ,  $\exists$  an edge  $e \in T - T'$   
s.t.  $(T - \{e\}) \cup \{e'\}$  is also a spanning tree.

Use this to show that one can  
"walk" from any spanning tree to  
a minimum spanning tree.



### 3. Clustering.

Given a set of objects e.g. texts, photos, micro-organisms etc we want to organize or classify these objects into "coherent" groups.

We assume that we are given a distance  $f$  on the objects with the understanding that objects with larger distance are less similar.

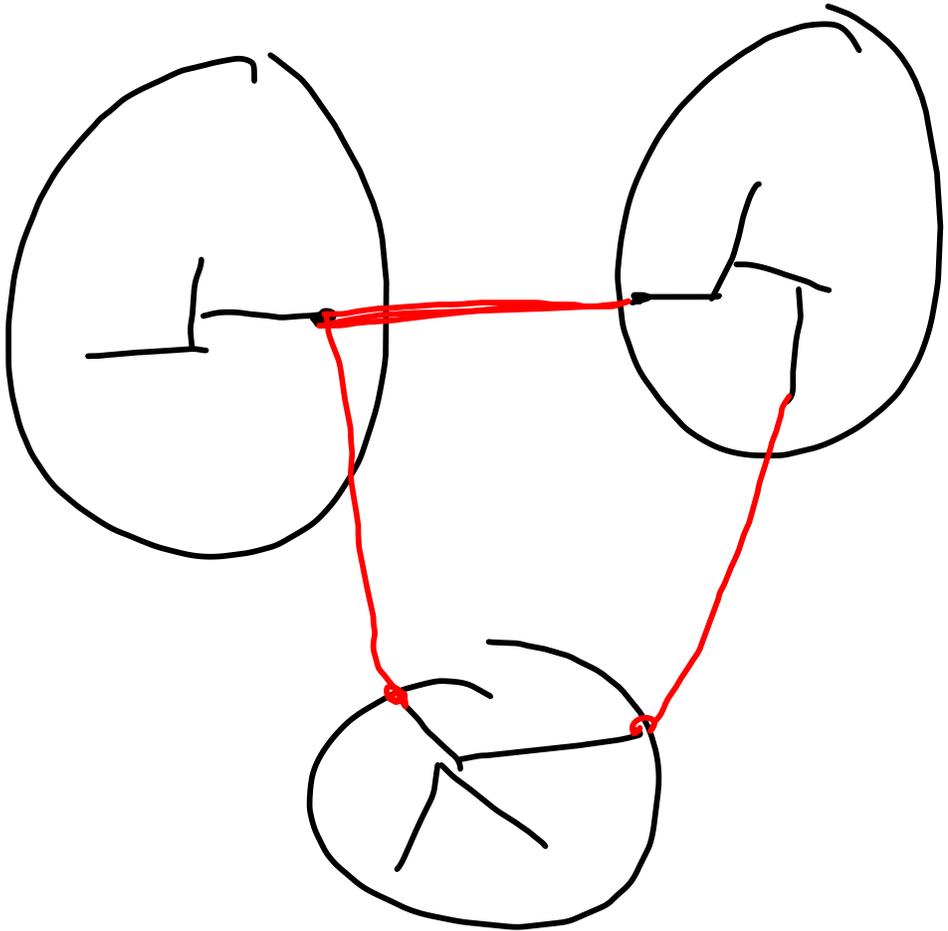
Thus given a distance  $f$  on the set of objects we seek to divide them into groups so that objects in the same group are "near" & objects in different groups are "far apart".

# Clustering with maximum spacing

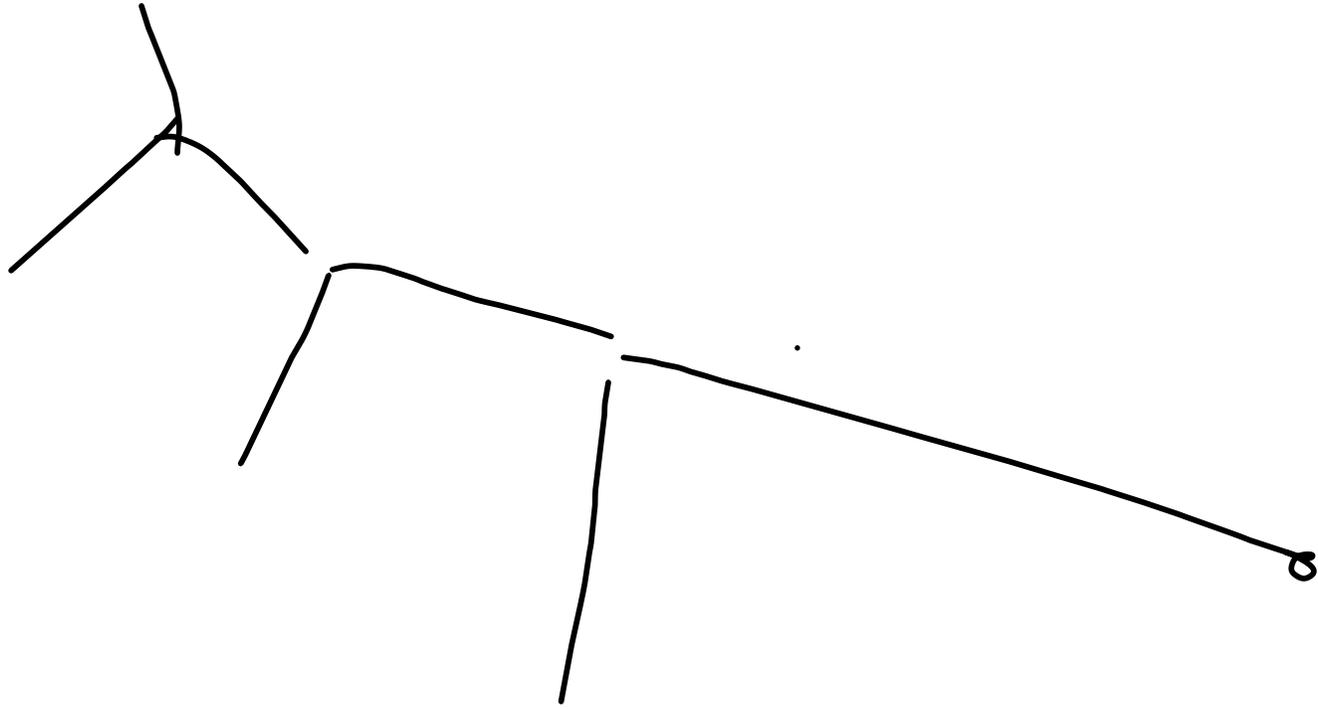
We are given a set  $U$  of  $n$  objects with labels  $p_1, p_2, \dots, p_n$ . We wish to partition  $U$  into  $k$  non-empty sets  $C_1, C_2, \dots, C_k$ . Such a partition is called

a  $k$ -clustering. We define the spacing

of a  $k$ -clustering to be the min. of any pair of pts in different clusters



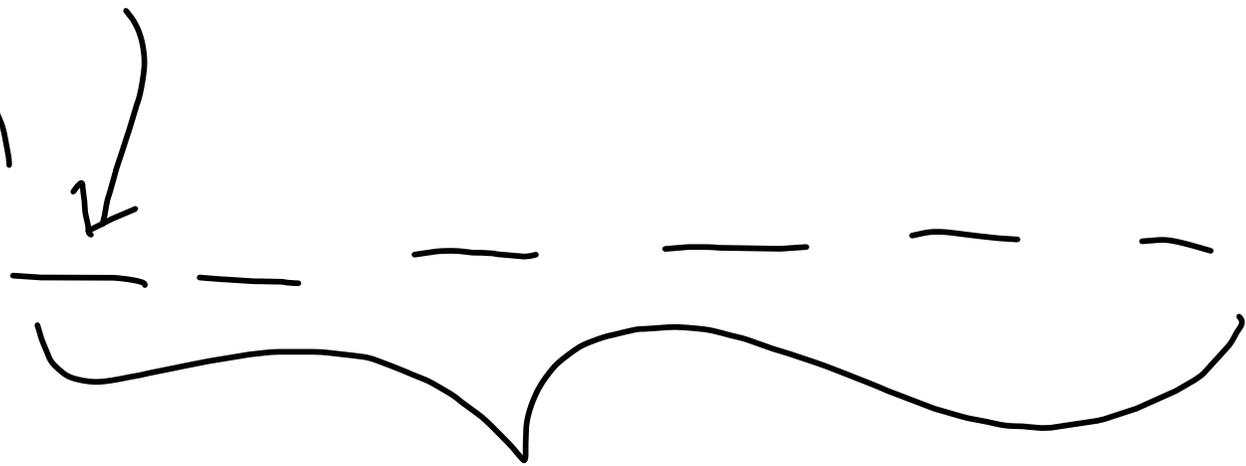
Our clustering problem is to find  
a  $k$ -clustering with maximum spacing



# The Algorithm

To set a  $k$ -clustering with maximum spacing we run Kruskal's algorithm for  $n-k$  steps

The remaining  $k-1 = (n-1) - (n-k)$  edges are the  $k-1$  most expensive edges of the MST



This is equivalent to summing  
the full Kruskal's alg. & then  
discarding the  $k-1$  most expensive  
edges. The first of these gives the  
spacing of the  $k$ -clustering obtain.